Types of Remotely Operated Vehicles (ROV)

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Long Range Navajo	SAAB ROV/AUV Hybrid	Streaming Vehicle	Long Range Crawler
Free swimming vehicle Swims through pipe	Free swimming vehicle Swims through pipe	Steamer vehicle Floats through pipe	Crawler vehicle Drives through pipe
Navigate complex structures including vertical shafts	Navigate complex structures including vertical shafts	Navigates through partially filled pipe sections	Drives through mixed dry and flooded pipe sections
Medium Flow	High Flow	High Flow	Dry
Color and low light monochrome camera Cross section sonar / map sediment buildup Forward looking navigation / feature detection sonar JD mapping / alignment Detect features in zero visibility water Metal thickness assessment Deployment Range up to 5,000 meters Depth to 305 meters Size—1194 mm X 610 mm X 420 mm	Color and low light monochrome camera Cross section sonar / map sediment buildup Forward looking navigation / feature detection sonar Journal mapping / alignment Detect features in zero visibility water Deployment Ranges exceeding 20 kilometers (tethered) Ranges up to 12 hrs (untethered)	Color and low light monochrome camera Cross section sonar / map sediment buildup 360 degree dual video camera pan and tilt Ground penetrating radar Deployment Range up to 2,100meters Size—3083 mm X 1418 mm	Services Color and low light monochrome camera Laser cross sections July Laser Scans Deployment Range up to 4,000meters Size—1388 mm X 945 mm X 1000 mm July Laser Sections
 Multibeam sonar option would add 305 mm to height 55 or 110 kgf thrust 	 Size—698.5 mm X 3657.6 mm X 419.1 mm Multibeam sonar option 		
Notes: Not restricted by slope of pipe Four function manipulator and tool attachments available	Notes: Not restricted by slope in pipe Navigate branches in tunnel Run untethered for more complex structures	Notes:	Notes:
Reporting: • Video DVD and Notes • Data Acquisition System	Reporting: Video DVD and Notes Data Acquisition System	Reporting: Video DVD and Notes Data Acquisition System	Reporting: • Video DVD and Notes • Data Acquisition System